

AAE 635

Applied Microeconomic Theory

Fall 2009

10/12/2009

Classes 12-13

Last class

- Cost minimization problem

Today & Next class (and more)

- Homework 3 due Oct. 20th
- Midterm in class on Oct. 22th
- Cost minimization
 - Two inputs and general case
- Duality (lecture note 8, chapters 3,5&6)
- Cost minimization (continued) (lecture note 9, chapter 3,5&6)

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Math Roadmap II

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Duality

- Primal approach: FONC's
- Dual approach: via indirect objective function
- The problem:
$$\underset{\mathbf{x}}{\text{Max}} \{ f(\mathbf{x}, \boldsymbol{\alpha}) : \mathbf{h}(\mathbf{x}, \boldsymbol{\alpha}) = 0, \mathbf{x} \geq 0, \mathbf{x} \in \mathbf{R}^n \}$$
 - Direct objective fn = $f(\mathbf{x}, \boldsymbol{\alpha})$
 - Indirect objective fn = $f(\mathbf{x}^*(\boldsymbol{\alpha}), \boldsymbol{\alpha}) = V(\boldsymbol{\alpha})$
- Envelop theorem: $\frac{\partial V}{\partial \boldsymbol{\alpha}} \equiv V_{\boldsymbol{\alpha}} = L_{\boldsymbol{\alpha}}(\mathbf{x}^*(\boldsymbol{\alpha}), \boldsymbol{\lambda}^*(\boldsymbol{\alpha}), \boldsymbol{\alpha})$
- Interpreting $\boldsymbol{\lambda}$

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The primal-dual approach

- Alternative SOCC: the bordered Hessian

$$\mathbf{H} \equiv \frac{\partial^2 L}{\partial (\mathbf{x}, \boldsymbol{\lambda})^2} \equiv \begin{bmatrix} L_{\mathbf{xx}} & (\mathbf{h}_{\mathbf{x}})^T \\ \mathbf{h}_{\mathbf{x}} & 0 \end{bmatrix} \text{ being negative definite,}$$

$$\text{s.t. } \mathbf{h}_{\mathbf{x}} \cdot \begin{bmatrix} \mathbf{v}_a \\ \mathbf{v}_b \end{bmatrix} = 0, \mathbf{v}_b \neq 0$$

- The primal-dual results (CQ, interior solution):

$$V_{aa} - L_{aa}(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\alpha}) = [L_{a\mathbf{x}}(\mathbf{x}^*, \boldsymbol{\lambda}^*), L_{a\boldsymbol{\lambda}}(\mathbf{x}^*, \boldsymbol{\lambda}^*)] \begin{bmatrix} \mathbf{x}_a^* \\ \boldsymbol{\lambda}_a^* \end{bmatrix},$$

symmetric and positive semi-definite

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Special cases

- Linear objective function: $f(\mathbf{x}, \boldsymbol{\alpha}) = \boldsymbol{\alpha}^T \cdot \mathbf{x}$
- Constraint functions do not contain $\boldsymbol{\alpha}$: $\mathbf{h}(\mathbf{x}) = 0$

- The primal-dual results (CQ, interior solution):

$$V_{aa} - L_{aa}(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\alpha}) = V_{aa} = [\mathbf{I}_n, 0] \begin{bmatrix} \mathbf{x}_a^* \\ \boldsymbol{\lambda}_a^* \end{bmatrix} = \mathbf{x}_a^*$$

Symmetric, positive semi-definite matrix

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Implications

- $V(\boldsymbol{\alpha})$ is homogeneous of degree one and convex in $\boldsymbol{\alpha}$ (why? because $V_{\boldsymbol{\alpha}\boldsymbol{\alpha}}$ is p.s.d...)
 - Convexity being a general property of $V(\boldsymbol{\alpha})$ for any linear obj. fn (does not rely on interior solution...)
- \mathbf{x} is homogeneous of degree zero in $\boldsymbol{\alpha}$
- $\mathbf{x}_{\boldsymbol{\alpha}}$ is symmetric and p.s.d (why?)

- What about minimization?

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Profit maximization

- Indirect profit function $V(\boldsymbol{\alpha})$
- Envelop theorem \rightarrow Hotelling Lemma
 - The profit maximizing netput demand functions are obtained via the derivative of indirect profit function with respect to the corresponding price
- Netput demand functions are homogeneous of degree zero in prices
- $\mathbf{x}_{\boldsymbol{\alpha}}$ is symmetric and p.s.d \rightarrow upward sloping output supply and downward sloping input demand, and symmetric restrictions

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Cost minimization

- Indirect cost function $V(\boldsymbol{\alpha})$
- Envelop theorem \rightarrow Shephard Lemma
 - The cost minimizing input demand functions are obtained via the derivative of indirect cost function with respect to the corresponding price
- Input demand functions are homogeneous of degree zero in prices
- $\mathbf{x}_{\boldsymbol{\alpha}}^c$ is symmetric and **n.s.d** \rightarrow downward sloping input demand and symmetric restrictions

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